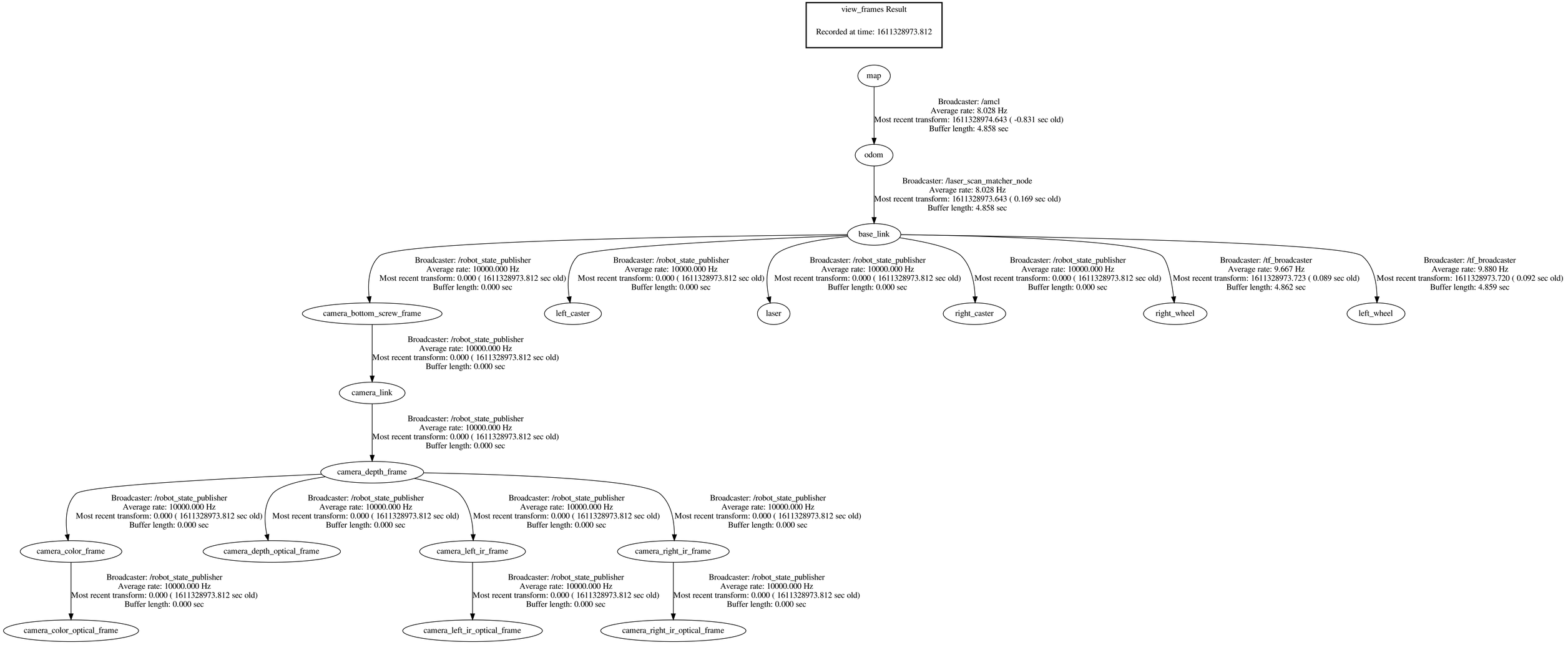
view_frames Result
Recorded at time: 1611328973.812
map
Broadcaster: /amcl
Average rate: 8.028 Hz
Most recent transform: 1611328974.643 ( -0.831 sec old)
Buffer length: 4.858 sec
odom
Broadcaster: /laser_scan_matcher_node
Average rate: 8.028 Hz
Most recent transform: 1611328973.643 ( 0.169 sec old)
Buffer length: 4.858 sec
base_link
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 ( 1611328973.812 sec old)
Buffer length: 0.000 sec
camera_bottom_screw_frame
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 ( 1611328973.812 sec old)
Buffer length: 0.000 sec
left_caster
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 ( 1611328973.812 sec old)
Buffer length: 0.000 sec
laser
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 ( 1611328973.812 sec old)
Buffer length: 0.000 sec
right_caster
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 ( 1611328973.812 sec old)
Buffer length: 0.000 sec
right_wheel
Broadcaster: /tf_broadcaster
Average rate: 9.667 Hz
Most recent transform: 1611328973.723 ( 0.089 sec old)
Buffer length: 4.862 sec
left_wheel
Broadcaster: /tf_broadcaster
Average rate: 9.880 Hz
Most recent transform: 1611328973.720 ( 0.092 sec old)
Buffer length: 4.859 sec
camera_link
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 ( 1611328973.812 sec old)
Buffer length: 0.000 sec
camera_depth_frame
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 ( 1611328973.812 sec old)
Buffer length: 0.000 sec
camera_color_frame
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 ( 1611328973.812 sec old)
Buffer length: 0.000 sec
camera_depth_optical_frame
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 ( 1611328973.812 sec old)
Buffer length: 0.000 sec
camera_left_ir_frame
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 ( 1611328973.812 sec old)
Buffer length: 0.000 sec
camera_right_ir_frame
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 ( 1611328973.812 sec old)
Buffer length: 0.000 sec
camera_color_optical_frame
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 ( 1611328973.812 sec old)
Buffer length: 0.000 sec
camera_left_ir_optical_frame
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 ( 1611328973.812 sec old)
Buffer length: 0.000 sec
camera_right_ir_optical_frame